The Journal of Nonlinear Sciences and Applications http://www.tjnsa.com

# RELATED FIXED POINT THEOREMS IN FUZZY METRIC SPACES

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ABSTRACT. We prove a related fixed point Theorem for four mappings which are not continuous in four fuzzy metric spaces, one of them is a sequentially compact fuzzy metric space. Our Theorem in the metric version generalizes Theorem 4 of [1]. Finally, We give a fuzzy version of Theorem 3 of [1].

### 1. INTRODUCTION AND PRELIMINARIES

The concept of fuzzy sets was introduced initially by Zadeh [11] in 1965. George and Veeramani [4] modified the concept of fuzzy metric space introduced by Kramosil and Michalek [6]. Recently, Fisher [3], Telci [10] and Aliouche and Fisher [1] proved some related fixed point Theorems in compact metric spaces. Motivated by a work due to Popa [7], we have observed that proving fixed point theorems using an implicit relation is a good idea since it covers several contractive conditions rather than one contractive condition. In this paper, we mainly prove a related fixed point Theorem for four mappings which are not necessarily continuous in four fuzzy metric spaces, using an implicit relation, one of them is a sequentially compact fuzzy metric space. One of our Theorems in the metric version generalizes a theorem of Aliouche and Fisher [1]. We give also a fuzzy version of Theorem 3 of [1].

**Definition 1.1** ([9]). A binary operation  $* : [0, 1] \times [0, 1] \longrightarrow [0, 1]$  is a continuous t-norm if it satisfies the following conditions:

1) \* is associative and commutative,

2) \* is continuous,

Date: Received: March 2008; Revised: Dec 2008

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<sup>2000</sup> Mathematics Subject Classification. Primary 47H10; Secondary 54H25.

Key words and phrases. Fuzzy metric space, implicit relation, sequentially compact Fuzzy metric space, related fixed point.

3) a \* 1 = a for all  $a \in [0, 1]$ ,

4)  $a * b \le c * d$  whenever  $a \le c$  and  $b \le d$ , for each  $a, b, c, d \in [0, 1]$ .

Two typical examples of a continuous t-norm are a \* b = ab and  $a * b = \min\{a, b\}$ .

**Definition 1.2** ([4]). A 3-tuple (X, M, \*) is called a fuzzy metric space if X is an arbitrary (non-empty) set, \* is a continuous t-norm a and M is a fuzzy set on  $X^2 \times (0, \infty)$  satisfying the following conditions for each  $x, y, z \in X$  and t, s > 0,

- 1) M(x, y, t) > 0,
- 2) M(x, y, t) = 1 if and only if x = y,
- 3) M(x, y, t) = M(y, x, t),
- 4)  $M(x, y, t) * M(y, z, s) \le M(x, z, t + s),$
- 5)  $M(x, y, .) : (0, \infty) \longrightarrow [0, 1]$  is continuous.

**Definition 1.3** ([3]). Let (X, M, \*) be a fuzzy metric space.

1) For t > 0, the open ball B(x, r, t) with center  $x \in X$  and radius 0 < r < 1 is defined by

$$B(x, r, t) = \{ y \in X : M(x, y, t) > 1 - r \}.$$

2) Let (X, M, \*) be a fuzzy metric space and  $\tau$  be the set of all  $A \subset X$  with  $x \in A$  if and only if there exist t > 0 and 0 < r < 1 such that  $B(x, r, t) \subset A$ . Then,  $\tau$  is a topology on X induced by the fuzzy metric M.

3) A sequence  $\{x_n\}$  in X converges to x if and only if for any  $0 < \epsilon < 1$  and t > 0, there exists  $n_0 \in \mathbb{N}$  such that for all  $n \ge n_0$ ,  $M(x_n, x, t) > 1 - \epsilon$ ; i.e.,  $M(x_n, x_m, t) \to 1$  as  $n \to \infty$  for all t > 0.

4) A sequence  $\{x_n\}$  in X is called a Cauchy sequence if and only if for any  $0 < \epsilon < 1$  and t > 0, there exists  $n_0 \in \mathbb{N}$  such that for all  $n, m \ge n_0$ ,  $M(x_n, x_m, t) > 1 - \epsilon$ ; i.e.,  $M(x_n, x_m, t) \to 1$  as  $n, m \to \infty$  for all t > 0.

5) A fuzzy metric space (X, M, t) in which every Cauchy sequence is convergent is said to be complete.

**Definition 1.4.** A subset A of X is said to be F-bounded if there exists t > 0 and 0 < r < 1 such that M(x, y, t) > 1 - r for all  $x, y \in A$ .

**Lemma 1.5** ([5]). Let (X, M, \*) be a fuzzy metric space. Then, M(x, y, t) is non-decreasing with respect to t, for all x, y in X.

**Lemma 1.6** ([5]). Let (X, M, \*) be a fuzzy metric space. Then, M is a continuous function on  $X^2 \times (0, \infty)$ .

**Definition 1.7.** (X, M, \*) is said to be sequentially compact fuzzy metric space if every sequence in X has a convergent sub-sequence in it.

Let  $\Phi$  be the set of all functions  $\phi : [0,1]^6 \longrightarrow [0,1]$  such that if either  $\phi(u,1,u,v,v,1) > 0$  or  $\phi(u,u,1,v,1,v) > 0$  for all  $u,v \in [0,1)$ , then u > v.

**Example 1.8.** Let  $\phi(t_1, t_2, t_3, t_4, t_5, t_6) = t_1 - \min\{t_2, t_3, t_4, t_5, t_6\}$ . Then  $\phi \in \Phi$ .

#### 2. Main results

**Theorem 2.1.** Let  $(X, M_1, \theta_1)$ ,  $(Y, M_2, \theta_2)$ ,  $(Z, M_3, \theta_3)$  and  $(W, M_4, \theta_4)$  be fuzzy metric spaces and  $B: X \longrightarrow Y, T: Y \longrightarrow Z$ ,  $A: Z \longrightarrow W, S: W \longrightarrow X$  be mappings satisfying

(1) 
$$\phi_1 \begin{pmatrix} M_1(SATy, SATBx, t), M_1(x, SATy, t), \\ M_1(x, SATBx, t), M_2(y, Bx, t), \\ M_2(y, BSATy, t), M_2(Bx, BSATy, t) \end{pmatrix} > 0$$

for all  $x \in X$ ,  $y \in Y$  with  $y \neq Bx$  and for all t > 0, where  $\phi_1 \in \Phi$ ,

(2) 
$$\phi_2 \begin{pmatrix} M_2(BSAz, BSATy, t), M_2(y, BSAz, t), \\ M_2(y, BSATy, t), M_3(z, Ty, t), \\ M_3(z, TBSAz, t), M_3(Ty, TBSAz, t) \end{pmatrix} > 0$$

for all  $z \in Z$ ,  $y \in Y$  with  $z \neq Ty$  and for all t > 0, where  $\phi_2 \in \Phi$ ,

(3) 
$$\phi_3 \begin{pmatrix} M_3(TBSw, TBSAz, t), M_3(z, TBSw, t), \\ M_3(z, TBSAz, t), M_4(w, Az, t), \\ M_4(w, ATBSw, t), M_4(Az, ATBSw, t) \end{pmatrix} > 0$$

for all  $z \in Z$ ,  $w \in W$  with  $w \neq Az$  and for all t > 0, where  $\phi_3 \in \Phi$ ,

(4) 
$$\phi_4 \begin{pmatrix} M_4(ATBx, ATBSw, t), M_4(w, ATBx, t), \\ M_4(w, ATBSw, t), M_1(x, Sw, t), \\ M_1(x, SATBx, t), M_1(Sw, SATBx, t) \end{pmatrix} > 0$$

for all  $x \in X$ ,  $w \in W$  with  $x \neq Sw$  and for all t > 0, where  $\phi_4 \in \Phi$ . Further, suppose that one of the following is true:

(a)  $(X, M_1, \theta_1)$  is sequentially compact and SATB is continuous on X.

(b)  $(Y, M_2, \theta_2)$  is sequentially compact and BSAT is continuous on Y.

(c)  $(Z, M_3, \theta_3)$  is sequentially compact and TBSA is continuous on Z.

(d)  $(W, M_4, \theta_4)$  is sequentially compact and ATBS is continuous on W.

Then, SATB has a unique fixed point  $u \in X$ , BSAT has a unique fixed point  $v \in Y$ , TBSA has a unique fixed point  $w \in Z$  and ATBS has a unique fixed point  $q \in W$ . Further, Bu = v, Tv = w, Aw = q and Sq = u.

*Proof.* Suppose that (a) holds. For every t > 0, define  $\phi(x) = M_1(x, SATBx, t)$  for all  $x \in X$ . Then, there exists  $p \in X$  such that  $\phi(p) = M_1(p, SATBp, t) = \max{\phi(x) : x \in X}$ .

Suppose that  $BSATBSATBp \neq BSATBSATBsATBp$ . Then,  $TBSATBp \neq TBSATBSATBp$ ,  $ATBp \neq ATBSATBp$  and  $p \neq SATBp$ .

Putting y = BSATBSATBp and x = SATBSATBSATBp in (1) we have

$$\phi_{1} \left( \begin{array}{c} M_{1}(SATBSATBSATBp, SATBSATBSATBSATBp, t), \\ M_{1}(SATBSATBSATBp, SATBSATBSATBp, t), \\ M_{1}(SATBSATBSATBp, SATBSATBSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBSATBp, t) \end{array} \right) > 0$$

and so

(5)  $\phi(SATBSATBSATBp) > M_2(BSATBSATBp, BSATBSATBSATBp, t).$ Putting y = BSATBSATBp and z = TBSATBp in (2) we get

$$\phi_{2} \begin{pmatrix} M_{2}(BSATBSATBp, BSATBSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBp, t), \\ M_{2}(BSATBSATBp, BSATBSATBp, t), \\ M_{3}(TBSATBp, TBSATBSATBp, t), \\ M_{3}(TBSATBp, TBSATBSATBp, t), \\ M_{3}(TBSATBp, TBSATBSATBp, t), \\ M_{3}(TBSATBp, TBSATBSATBp, t) \end{pmatrix} > 0.$$

Therefore

(6) 
$$M_2(BSATBSATBp, BSATBSATBSATBp, t)$$
  
>  $M_3(TBSATBp, TBSATBSATBp, t)$ 

Putting z = TBSATBp and w = ATBp in (3) we obtain

$$\phi_{3} \begin{pmatrix} M_{3}(TBSATBp, TBSATBSATBp, t), \\ M_{3}(TBSATBp, TBSATBp, t), \\ M_{3}(TBSATBp, TBSATBSATBp, t), \\ M_{4}(ATBp, ATBSATBp, t), \\ M_{4}(ATBp, ATBSATBp, t), \\ M_{4}(ATBSATBp, ATBSATBp, t), \end{pmatrix} > 0$$

and so

(7) 
$$M_3(TBSATBp, TBSATBSATBp, t) > M_4(ATBp, ATBSATBp, t).$$

Putting w = ATBp and x = p in (4) we have

$$\phi_4 \left( \begin{array}{c} M_4(ATBp, ATBSATBp, t), M_4(ATBp, ATBp, t), \\ M_4(ATBP, ATBSATBp, t), M_1(p, SATBp, t), \\ M_1(p, SATBp, t), M_1(SATBp, SATBp, t) \end{array} \right) > 0.$$

Hence

(8) 
$$M_4(ATBp, ATBSATBp, t) > M_1(p, SATBp, t) = \phi(p).$$

From (5), (6), (7) and (8) we get  $\phi(SATBSATBSATBp) > \phi(p)$  which is a contradiction. Therefore

(9) BSATBSATBp = BSATBSATBSATBp.

Denote  $BSATBSATBp = v \in Y$ . Then from (9), v = BSATv. Let  $Tv = w \in Z$ ,  $Aw = q \in W$ ,  $Sq = u \in X$ . Then v = BSATv = BSAw = BSq = Bu. Also, SATBu = SATv = SAw = Sq = u, TBSAw = TBSq = TBu = Tv = wand ATBSq = ATBu = ATv = Aw = q.

For the uniqueness of u, suppose that SATBu' = u' with  $u \neq u'$ . Then,  $SATBu \neq SATBu'$ ,  $ATBu \neq ATBu'$ ,  $TBu \neq TBu'$  and  $Bu \neq Bu'$ .

Putting x = u and y = Bu' in (1) we have

$$\phi_1 \left( \begin{array}{c} M_1(SATBu', SATBu, t), M_1(u, SATBu', t), \\ M_1(u, SATBu, t), M_2(Bu', Bu, t), \\ M_2(Bu', BSATBu', t), M_2(Bu, BSATBu', t) \end{array} \right) > 0$$

and so

$$M_1(u, u', t) > M_2(Bu, Bu', t)....(10).$$

Putting z = TBu, y = Bu' in (2) we get

$$\phi_2 \left( \begin{array}{c} M_2(BSATBu, BSATBu', t), M_2(Bu', BSATBu, t), \\ M_2(Bu', BSATBu', t), M_3(TBu, TBu', t), \\ M_3(TBu, TBSATBu, t), M_3(TBu', TBSATBu, t) \end{array} \right) > 0.$$

Therefore

$$M_2(Bu, Bu', t) > M_3(TBu, TBu', t)....(11)$$

Putting z = TBu, w = ATBu' in (3) we obtain

$$\phi_3 \left( \begin{array}{c} M_3(TBSATBu', TBSATBu, t), M_3(TBu, TBSATBu', t), \\ M_3(TBu, TBSATBu, t), M_4(ATBu', ATBu, t), \\ M_4(ATBu', ATBSATBu', t), M_4(ATBu, ATBSATBu', t) \end{array} \right) > 0.$$

Hence

$$M_3(TBu, TBu', t) > M_4(ATBu, ATBu', t)....(12)$$

Putting x = SATBu, w = ATBu' in (4) we have

$$\phi_4 \left( \begin{array}{c} M_4(ATBSATBu, ATBSATBu', t), M_4(ATBu', ATBSATBu, t), \\ M_4(ATBu', ATBSATBu', t), M_1(SATBu, SATBu', t), \\ M_1(SATBu, SATBSATBu, t), M_1(SATBu', SATBSATBu, t)) \end{array} \right) > 0$$

and so

$$M_4(ATBu, ATBu', t) > M_1(u, u', t)....(13)$$

Using (10), (11), (12) and (13) we get

$$M_1(u, u', t) > M_1(u, u', t)$$

which is a contradiction. Hence, u is the unique fixed point of SATB. Similarly, we can prove the uniqueness of fixed points of BSAT, TBSA and ATBS. In a similar manner, the Theorem holds if either (b) or (c) or (d) is true.

The following Example illustrates Theorem 2.1.

Example 2.2. Let 
$$X = [0,1], Y = [1,2), Z = (2,3]$$
 and  $W = [3,4)$  and  $M_1(x,y,t) = \frac{t}{t+|x-y|}, M_2(y,z,t) = \frac{t}{t+|y-z|}, M_3(z,w,t) = \frac{t}{t+|z-w|}$  and  $M_4(w,x,t) = \frac{t}{t+|w-x|}.$   
Define  $B: X \longrightarrow Y$  by:  
 $Bx = \begin{cases} 1 & \text{if } x \in [0,3/4], \\ 3/2 & \text{if } x \in (3/4,1]. \end{cases}$ 

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$$T: Y \longrightarrow Z \text{ by } Ty = 3 \text{ for all } y \in Y, A: Z \longrightarrow W \text{ by}$$
$$Az = \begin{cases} 7/2 & \text{if } x \in (2, 5/2], \\ 3 & \text{if } x \in (5/2, 3]. \end{cases}$$

and  $S: W \longrightarrow X$  by Sw = 1 for all  $w \in W$ . Let

$$\phi_1(t_1, t_2, t_3, t_4, t_5, t_6) = t_1 - \min\{t_2, t_3, t_4, t_5, t_6\}$$
 and  
 $\phi_1 = \phi_2 = \phi_3 = \phi_4.$ 

In this Example, the inequalities (1), (2), (3) and (4) are satisfied since the value of the left hand side of each inequality is 1. Clearly, SATB(1) = 1, BSAT(3/2) = 3/2, TBSA(3) = 3, ATBS(3) = 3 and

B1 = 3/2, T(3/2) = 3, A3 = 3, S3 = 1.

If B = T, T = S, A = R, S = I (Identity map) and W = X in Theorem 2.1 we get the following Theorem.

**Theorem 2.3.** Let  $(X, M_1, \theta_1)$ ,  $(Y, M_2, \theta_2)$  and  $(Z, M_3, \theta_3)$  be fuzzy metric spaces and  $T: X \longrightarrow Y$ ,  $S: Y \longrightarrow Z$ ,  $R: Z \longrightarrow X$  be mappings satisfying

(1) 
$$\phi_1 \left( \begin{array}{c} M_1(RSy, RSTx, t), M_1(x, RSy, t), M_1(x, RSTx, t), \\ M_2(y, Tx, t), M_2(y, TRSy, t), M_2(Tx, TRSy, t) \end{array} \right) > 0$$
  
for all  $x \in X, y \in Y$  with  $y \neq Tx$  and for all  $t > 0$ , where  $\phi_1 \in \Phi$ ,

(2) 
$$\phi_2 \left( \begin{array}{c} M_2(TRz, TRSy, t), M_2(y, TRz, t), M_2(y, TRSy, t), \\ M_3(z, Sy, t), M_3(z, STRz, t), M_3(Sy, STRz, t) \end{array} \right) > 0$$

for all  $z \in Z$ ,  $y \in Y$  with  $z \neq Sy$  and for all t > 0, where  $\phi_2 \in \Phi$ ,

(3) 
$$\phi_3 \begin{pmatrix} M_3(STx, STRz, t), M_3(z, STx, t), M_3(z, STRz, t), \\ M_1(x, Rz, t), M_1(x, RSTx, t), M_1(Rz, RSTx, t) \end{pmatrix} > 0$$

for all  $z \in Z$ ,  $x \in X$  with  $x \neq Rz$  and for all t > 0, where  $\phi_3 \in \Phi$ . Further, suppose that one of the following is true:

(a)  $(X, M_1, \theta_1)$  is sequentially compact and RST is continuous on X.

(b)  $(Y, M_2, \theta_2)$  is sequentially compact and TRS is continuous on Y.

(c)  $(Z, M_3, \theta_3)$  is sequentially compact and STR is continuous on Z.

Then, RST has a unique fixed point  $u \in X$ , TRS has a unique fixed point  $v \in Y$ and STR has a unique fixed point  $w \in Z$ . Further, Tu = v, Sv = w and Rw = u.

If R = I (Identity map) and Z = X in Theorem 2.3 we obtain

**Theorem 2.4.** Let  $(X, M_1, \theta_1)$  and  $(Y, M_2, \theta_2)$  be fuzzy metric spaces and  $T : X \longrightarrow Y, S : Y \longrightarrow X$  be mappings satisfying

$$(1) \ \phi_1 \left( \begin{array}{c} M_1(Sy, STx, t), M_1(x, Sy, t), M_1(x, STx, t), \\ M_2(y, Tx, t), M_2(y, TSy, t), M_2(Tx, TSy, t) \end{array} \right) > 0 \\ for \ all \ x \in X, \ y \in Y \ with \ y \neq Tx \ and \ for \ all \ t > 0, \ where \ \phi_1 \in \Phi, \\ (2) \ \phi_2 \left( \begin{array}{c} M_2(Tx, TSy, t), M_2(y, Tx, t), M_2(y, TSy, t), \\ M_1(x, Sy, t), M_1(x, STx, t), M_1(Sy, STx, t) \end{array} \right) > 0 \\ for \ all \ x \in X, \ y \in Y \ with \ y \neq Tx \ and \ for \ all \ t > 0, \ where \ \phi_1 \in \Phi, \\ (2) \ \phi_2 \left( \begin{array}{c} M_2(Tx, TSy, t), M_2(y, Tx, t), M_2(y, TSy, t), \\ M_1(x, Sy, t), M_1(x, STx, t), M_1(Sy, STx, t) \end{array} \right) > 0 \\ for \ where \ \phi_1 \in \Phi, \ where \ \phi_1 \in \Phi, \\ (2) \ \phi_2 \left( \begin{array}{c} M_2(Tx, TSy, t), M_2(y, Tx, t), M_2(y, TSy, t), \\ M_1(x, Sy, t), M_1(x, STx, t), M_1(Sy, STx, t) \end{array} \right) > 0 \\ for \ here \ here$$

for all  $x \in X$ ,  $y \in Y$  with  $x \neq Sy$  and for all t > 0, where  $\phi_2 \in \Phi$ . Further, suppose that one of the following is true:

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(a)  $(X, M_1, \theta_1)$  is sequentially compact and ST is continuous on X.

(b)  $(Y, M_2, \theta_2)$  is sequentially compact and TS is continuous on Y.

Then, ST has a unique fixed point  $u \in X$  and TS has a unique fixed point  $v \in Y$ . Further, Tu = v and Sv = u.

1) The metric version of Theorem 2.4 in compact metric spaces generalizes and improves Theorem 4 of Aliouche and Fisher [1] under the implicit relation  $\phi : \mathbb{R}^6_+ \to \mathbb{R}$  such that  $\phi(u, u, 0, v, 0, v) < 0$  or  $\phi(u, 0, u, v, v, 0) < 0$  implies u < v. 2) If  $\phi_1(t_1, t_2, t_3, t_4, t_5, t_6) = \phi_2(t_1, t_2, t_3, t_4, t_5, t_6) = t_1 - \min\{t_2, t_3, t_4, t_5, t_6\}$  in

Theorem 2.4, we get a fuzzy version of a Theorem of Fisher [3]. Finally, we give a fuzzy version of Theorem 3 of Aliouche and Fisher [1] using the following implicit relations.

We denote by  $\Psi$  the set of all functions  $\psi: [0,1]^4 \longrightarrow [0,1]$  such that

:(i)  $\psi$  is upper semi continuous in each coordinate variable,

(ii)  $\psi$  is decreasing in 3rd and 4th variable,

(iii) if either  $\psi(u, v, 1, u) \ge 0$  or  $\psi(u, 1, v, 1) \ge 0$  or  $\psi(u, v, u, 1) \ge 0$  for all  $u, v \in [0, 1]$ , then  $u \ge v$ .

Example 2.5.  $\psi(t_1, t_2, t_3, t_4) = t_1 - \min\{t_2, t_3, t_4\},\$ 

**Example 2.6.**  $\psi(t_1, t_2, t_3, t_4) = t_1 - \phi_1(\min\{t_2, t_3, t_4\})$ , where  $\phi_1 : (0, 1] \longrightarrow (0, 1]$  is an increasing and continuous function with  $\phi(t) > t$  for 0 < t < 1. For example  $\phi_1(t) = \sqrt{t}$  or  $\phi_1(t) = t^h$  for 0 < h < 1.

We need the following Lemma of [2].

**Lemma 2.7** ([2]). Let  $\{x_n\}$  be a sequence in a fuzzy metric space (X, M, \*) with  $M(x, y, t) \longrightarrow 1$  as  $t \longrightarrow \infty$  for all  $x, y \in X$ . If there exists a number  $k \in (0, 1)$  such that

$$M(x_{n+1}, x_n, kt) \ge M(x_n, x_{n-1}, t)$$

for all t > 0 and n = 1, 2, 3, ..., then  $\{x_n\}$  is a Cauchy sequence in X.

**Theorem 2.8.** Let  $(X, M_1, \theta_1)$  and  $(Y, M_2, \theta_2)$  be complete fuzzy metric spaces with  $M_1(x, x', t) \longrightarrow 1$  as  $t \longrightarrow \infty$  for all  $x, x' \in X$  and  $M_2(y, y', t) \longrightarrow 1$  as  $t \longrightarrow \infty$  for all  $y, y' \in Y$ . Let  $T : X \longrightarrow Y$ ,  $S : Y \longrightarrow X$  be mappings satisfying:

(1) 
$$\psi_1(M_1(Sy, STx, kt), M_2(y, Tx, t), M_1(x, Sy, t), M_1(x, STx, t)) \ge 0,$$

(2)  $\psi_2(M_2(Tx, TSy, kt), M_1(x, Sy, t), M_2(y, Tx, t), M_2(y, TSy, t)) \geq 0$ 

for all  $x \in X$ ,  $y \in Y$  and for all t > 0, where  $\psi_1, \psi_2 \in \Psi$  and 0 < k < 1. Then, ST has a unique fixed point  $u \in X$  and TS has a unique fixed point  $v \in Y$ . Further, Tu = v and Sv = u.

*Proof.* Let  $x_0$  be an arbitrary point in X. We define the sequences  $\{x_n\}$  and  $\{y_n\}$  in X and Y respectively by:  $y_n = Tx_{n-1}$ ,  $x_n = Sy_n$  for n = 1, 2, ...Putting  $x = x_n$  and  $y = y_n$  in (1), we have

$$\psi_1(M_1(x_n, x_{n+1}, kt), M_2(y_n, y_{n+1}, t), 1, M_1(x_n, x_{n+1}, t)) \ge 0$$

Since  $\psi_1$  is decreasing in 4th variable, we get

$$\psi_1(M_1(x_n, x_{n+1}, kt), M_2(y_n, y_{n+1}, t), 1, M_1(x_n, x_{n+1}, kt)) \ge 0.$$

From (iii), we obtain

$$M_1(x_n, x_{n+1}, kt) \ge M_2(y_n, y_{n+1}, t)...(3)$$

Putting  $x = x_{n-1}$  and  $y = y_n$  in (2), we have

$$\psi_2(M_2(y_n, y_{n+1}, kt), M_1(x_{n-1}, x_n, t), 1, M_2(y_n, y_{n+1}, t)) \ge 0.$$

As  $\psi_2$  is decreasing in 4th variable, we get

$$\psi_2(M_2(y_n, y_{n+1}, kt), M_1(x_{n-1}, x_n, t), 1, M_2(y_n, y_{n+1}, kt)) \ge 0.$$

From (iii), we obtain

$$M_2(y_n, y_{n+1}, kt) \ge M_1(x_{n-1}, x_n, t)....(4).$$

Using (3) and (4) we have for n = 1, 2, ...

$$M_1(x_n, x_{n+1}, t) \ge M_1(x_{n-1}, x_n, t/k^2)$$
 and  
 $M_2(y_n, y_{n+1}, t) \ge M_2(y_{n-1}, y_n, t/k^2).$ 

From Lemma 2.7, it follows that  $\{x_n\}$  and  $\{y_n\}$  are Cauchy sequences in X and Y respectively. Hence,  $\{x_n\}$  converges to  $u \in X$  and  $\{y_n\}$  converges to  $v \in Y$ . Putting  $x = x_{n-1}$  and y = v in (1), we get

$$\psi_1(M_1(Sv, STx_{n-1}, kt), M_2(v, Tx_{n-1}, t), M_1(x_{n-1}, Sv, t), M_1(x_{n-1}, STx_{n-1}, t)) \ge 0$$
  
Letting  $n \longrightarrow \infty$ , we have

$$\psi_1(M_1(Sv, u, kt), 1, M_1(u, Sv, t), 1) \ge 0.$$

Using (iii), we obtain

$$M_1(Sv, u, kt) \ge M_1(u, Sv, t)$$

and so Sv = u. Similarly, we can show that Tu = v. Now, STu = Sv = u and TSv = Tu = v.

To prove the uniqueness of u, suppose that ST has a second fixed point u' in X. Putting x = u', y = v in (1), we get

$$\psi_1(M_1(u, u', kt), M_2(Tu, Tu', t), M_1(u', u, t), 1)) \ge 0.$$

Since  $\psi_1$  is decreasing in 3rd variable, we have

$$\psi_1(M_1(u, u', kt), M_2(Tu, Tu', t), M_1(u', u, kt), 1)) \ge 0.$$

From (iii), we obtain

$$M_1(u, u', kt) \ge M_2(Tu, Tu', t).$$

Similarly, we have

$$M_2(Tu, Tu', kt) \ge M_1(u, u', t).$$

Hence

$$M_1(u, u', t) \ge M_1(u, u', t/k^2)$$

and so u = u'. The uniqueness of v follows in a similar manner.

1) If  $\psi_1(t_1, t_2, t_3, t_4) = \psi_2(t_1, t_2, t_3, t_4) = t_1 - \min\{t_2, t_3, t_4\}$  in Theorem 2.7, we get a fuzzy version of a Theorem of Fisher [3].

2) As in Theorems 2.4 and 2.7, we can obtain fuzzy versions of Theorems of [9].

The following Example support our Theorem 2.7.

**Example 2.9.** Let X = [0,1] = Y and  $M_1(x,y,t) = M_2(y,x,t) = \frac{t}{t+|x-y|}$ for all  $x, y \in X$  and for all t > 0. Define  $T : X \longrightarrow Y$  and  $S : Y \longrightarrow X$  by:

$$Tx = \begin{cases} x/2 & \text{if } x \in (0,1], \\ 1/2 & \text{if } x = 0. \end{cases},$$

Sy = 1/2 for all  $y \in Y$ . Let

$$\psi_1(t_1, t_2, t_3, t_4) = \psi_2(t_1, t_2, t_3, t_4) = t_1 - \min\{t_2, t_3, t_4\}.$$

In this Example, the inequality (1) is satisfied since the value of the left hand side of inequality is 1 and the inequality (2) is satisfied with k = 1/2. Clearly, ST(1/2) = 1/2, TS(1/4) = 1/4, S(1/4) = 1/2 and T(1/2) = 1/4.

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